

Cloth Simulation in the SILC Matrix Computation Framework: A Case Study

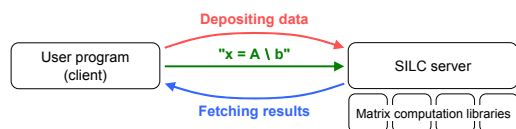
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Outline

- The SILC matrix computation framework
 - Easy-to-use interface for matrix computation libraries
 - Proposed application styles for numerical simulations in SILC
- Case study: Cloth simulation in SILC
- Experimental results
- Concluding remarks

Overview of the SILC framework

- **S**imple **I**nterface for **L**ibrary **C**ollections
 - Independent of libraries, environments & languages
 - Easy to use
- Three steps to use libraries
 - **Depositing data** (matrices, vectors, etc.) to a server
 - **Making requests for computation** by means of mathematical expressions
 - **Fetching the results of computation** if necessary



Example: Using SILC in C

```

silk_envelope_t A, C, u;
/* create matrices A, C and vector u_0 */
SILC_PUT("A", &A);
SILC_PUT("C", &C);
SILC_PUT("u", &u); /* u_0 */
for (k = 1; k <= n_steps; k++)
{
  SILC_EXEC("b = C * u");
  SILC_EXEC("u = A \ b");
  SILC_GET(&u, "u"); /* u_k */
/* output solution u_k at time t_k */
}
    
```

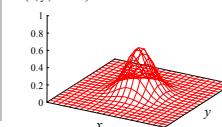
Solve the initial value problem of 2D diffusion equation below using the Crank-Nicolson method:

$$\frac{\partial u}{\partial t} = \frac{\partial^2 u}{\partial x^2} + \frac{\partial^2 u}{\partial y^2}, \quad x, y \in (0, 1),$$

$$u(x, y, t) = 0, \quad t > 0,$$

$$u(x, y, 0) = \begin{cases} 1 & \text{if } x, y \in (0.4, 0.6) \\ 0 & \text{otherwise} \end{cases}$$

$u(x, y, 0.004)$



Main characteristics of SILC

- Independence from programming languages
 - User programs for SILC in your favorite languages
- Independence from libraries and environments
 - Using alternative libraries and environments requires no modification in user programs
 - Flexible combinations of client & server environments

User program (client)	SILC server
Sequential	Sequential
Sequential	Shared-memory parallel (OpenMP)
Sequential	Distributed parallel (MPI)
Distributed parallel (MPI)	Distributed parallel (MPI)

Proposed application styles

- **Limited application style**
 - Use SILC only in the most time-consuming, computationally intensive part of a program
- **Comprehensive application style**
 - Move all relevant data to a SILC server, and implement overall simulations using SILC's mathematical expressions

Abbreviations:

- **LTD** for the limited application style
- **CMP** for the comprehensive application style

Comparison of LTD & CMP styles

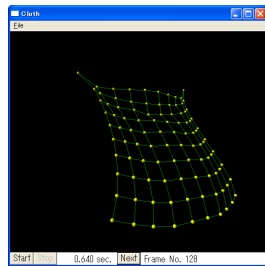
	LTD style	CMP style
Pros	<ul style="list-style-type: none"> • Easy to apply 	<ul style="list-style-type: none"> • Less data transfer • More parallelizable computations
Cons	<ul style="list-style-type: none"> • Frequent data transfer to/from the SILC server 	<ul style="list-style-type: none"> • May require a major rewrite of programs

Purposes of the present research

- To verify the feasibility of numerical simulations in SILC
- To examine the pros and cons of the two application styles

A case study: Cloth simulation

- Time-dependent simulation of cloth motion
 - Mass-spring model
 - The implicit Euler method
 - Solving a sparse linear system is necessary for each time step
- Original code
 - Sequential program in C
 - The CG method in the Lis iterative solvers library
 - Visualization via OpenGL



The original code

Do some initialization (defining cloth geometry, etc.)
For each time step:

1. Calculate force f and its derivatives $\partial f / \partial x$ and $\partial f / \partial v$ (Jacobian matrices).

2. Solve a linear system $A \Delta v = b$, where

$$A = \left\{ M - \Delta t^2 \frac{\partial f}{\partial x} - \Delta t \frac{\partial f}{\partial v} \right\}$$

$$b = \left\{ f_0 + \Delta t \frac{\partial f}{\partial x} v_0 \right\} \Delta t$$

3. Update particle motion.

$$v = v_0 + \Delta v$$

$$x = x_0 + \Delta t v$$

New code in the LTD style

Original code using Lis*

```
LIS_MATRIX A; LIS_VECTOR b, dv;
for (k = 1; k <= n_steps; k++)
{
    /* 1. Calculate f, df/dx and df/dv */
    ...
    /* 2. Solve AΔv = b */
    lis_solve(A, b, dv, /* Δv */
             lis_params,
             lis_options,
             lis_status);
    /* 3. Update particle motion */
    ...
}
```

New code using SILC

```
silc_envelope_t A, b, dv;
for (k = 1; k <= n_steps; k++)
{
    /* 1. Calculate f, df/dx and df/dv */
    ...
    /* 2. Solve AΔv = b */
    SILC_PUT("A", &A);
    SILC_PUT("b", &b);
    SILC_EXEC("dv = A \ \ b");
    SILC_GET(&dv, "dv"); /* Δv */
    /* 3. Update particle motion */
    ...
}
```

* An iterative solvers library written in C.

Force and its derivatives

- Force

$$f_i = \sum_{j \in P_i} (f_{ij} + d_{ij})$$

$$f_{ij} = b_k \left(|x_j - x_i| - l_k \right) \frac{x_j - x_i}{|x_j - x_i|} \quad (\text{spring force})$$

$$d_{ij} = -h_k (v_i - v_j) \quad (\text{damping})$$

- Derivatives (Jacobian matrices)

$$\frac{\partial f}{\partial x} = \begin{pmatrix} \frac{\partial f_1}{\partial x_1} & \dots & \frac{\partial f_1}{\partial x_n} \\ \vdots & \ddots & \vdots \\ \frac{\partial f_n}{\partial x_1} & \dots & \frac{\partial f_n}{\partial x_n} \end{pmatrix}, \quad \frac{\partial f}{\partial v} = \begin{pmatrix} \frac{\partial f_1}{\partial v_1} & \dots & \frac{\partial f_1}{\partial v_n} \\ \vdots & \ddots & \vdots \\ \frac{\partial f_n}{\partial v_1} & \dots & \frac{\partial f_n}{\partial v_n} \end{pmatrix}$$

Elements of the derivatives

- Off-diagonal blocks (3×3 submatrices)

$$\frac{\partial f_i}{\partial x_j} = b_k I - \frac{b_k l_k}{|x_j - x_i|} \left(I - \frac{(x_j - x_i)(x_j - x_i)^T}{|x_j - x_i|^2} \right), \quad \frac{\partial f_i}{\partial v_j} = h_k I$$

- Diagonal blocks (3×3 submatrices)

$$\frac{\partial f_i}{\partial x_i} = \sum_{j \in P_i} \left(-\frac{\partial f_i}{\partial x_j} \right), \quad \frac{\partial f_i}{\partial v_i} = \sum_{j \in P_i} \left(-\frac{\partial f_i}{\partial v_j} \right)$$

- Computing these blocks one after another is not a good idea in SILC (too fine-grain to parallelize)

Exploiting data parallelism

Original

For each spring k connecting particles i and j :

$$p_k = x_i - x_j \\ z_k = \text{sqrt}(\text{dot}(p_k, p_k))$$

CMP style

n : number of particles, s : number of springs

Y_1, Y_2 : linear maps from \mathbf{R}^{3n} to \mathbf{R}^{3s}
 X : another linear map from \mathbf{R}^{3s} to \mathbf{R}^s

$$p = (Y_1 - Y_2) x \\ z = \text{sqrt}(X(p * @ p))$$

*@: elementwise multiplication operator in SILC

All coarse-grain, parallelizable matrix computations

```
silc_envelope_t v, x;
```

```
/* 1. Calculate f, df/dx and df/dv */
SILC_EXEC("p = Y * x");
SILC_EXEC("z = sqrt(X_T * (p * @ p))");
SILC_EXEC("fij = p * @ (X * (K_stiff * @ (z - L)"));
SILC_EXEC("dij = (Y * v) * @ (X * K_damp)");
SILC_EXEC("f = Mg - Y_T * (fij + dij)");
```

```
SILC_EXEC("zhat = ones(s, 1) / @ z");
SILC_EXEC("pzhat = p * @ (X * zhat)");
SILC_EXEC("U_L = sparse(U_L_row, U_L_col, pzhat, 3*n, s)");
SILC_EXEC("U_R = sparse(U_R_row, U_R_col, pzhat, 3*n, s)");
SILC_EXEC("tmp = sqrt(zhat * @ K_stiff * @ L)");
SILC_EXEC("A2 = Y_T * diag(X * tmp); T2 = A2 * A2'");
SILC_EXEC("A3 = (U_L - U_R) * diag(tmp); T3 = A3 * A3'");
SILC_EXEC("Dfpx = T1 - T2 + T3");
```

```
/* 2. Solve A*Δv = b */
SILC_EXEC("A = M + (dt * dt) * Dfpx + dt * Dfvp");
SILC_EXEC("b = dt * (f - dt * (Dfpx * v))");
SILC_EXEC("dv = A \ b");
```

```
/* 3. Update particle motion */
SILC_EXEC("v += dv * @ fixed");
SILC_EXEC("x += dt * v");
SILC_GET(&v, "v");
SILC_GET(&x, "x");
```

New code in the CMP style: All expressions are **coarse-grain matrix computations** to be efficiently parallelized by a parallel SILC server.

Solving $A \Delta v = b$ is done in the same way as the LTD style.

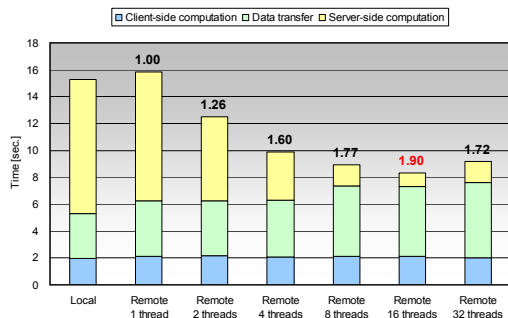
Experimental results

- 10^4 particles (7.998×10^8 springs), 20 time steps
- 3 user programs on the same PC
- A SILC server on the same PC
- Another server on SGI Altix 3700 in a GbE LAN

User program	Original	LTD version		CMP version
		PC (sequential)	Altix (16 threads)	Altix (32 threads)
SILC server	—			
Execution time [sec]	11.80	15.28	8.33	29.87
Speedup	—	x1.29 slower	x1.42 faster	x2.53 slower

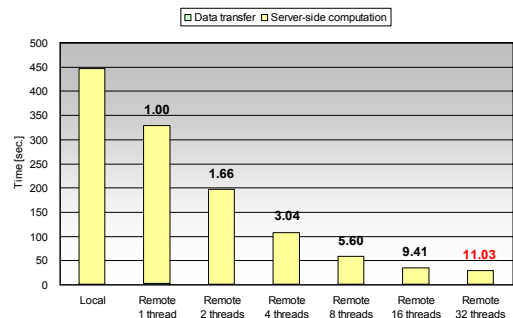
PC: Intel Pentium 4 3.40 GHz, 1 GB RAM, Microsoft Windows XP SP2
 SGI Altix 3700: Intel Itanium 2 1.3 GHz × 32, 32 GB RAM (cc-NUMA), Red Hat Linux AS 2.1

Performance of the LTD version



✓ Amount of data transfer per time step: 17.7 MB

Performance of the CMP version



✓ Amount of data transfer per time step: 0.458 MB (2.59%)

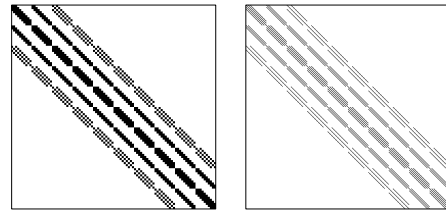
Performance of the CMP version (cont'd)

- The CMP version is slow because there are *lots of non-floating point operations* in sparse matrix computations in the Compressed Row Storage (CRS) format
- In fact, the FLOP count is about 20% fewer than the original and LTD versions

Sparse matrix-matrix products	53.57 %
Sparse matrix transpositions	20.04 %
Calls for the "sparse" function	11.48 %
Sparse matrix-matrix additions	7.13 %
Calls for the linear solver (CG)	4.59 %
Others	3.19 %

Breakdown of the server-side computation (32 threads)

Non-zero blocks in the derivatives



$$\frac{\partial f}{\partial x}$$

$$\frac{\partial f}{\partial v}$$

- ✓ Use of a block matrix storage format may accelerate the CMP version

Summary

- A feasibility study of numerical simulations in SILC
 - LTD and CMP versions of an existing cloth simulation code were developed
 - Pros and cons of the application styles were verified
- Future work
 - Performance improvements of the CMP version by means of a block matrix storage format
 - Further case studies with other types of numerical simulations such as CFD

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- A short demo of SILC and copies of our papers are available
- SILC v1.2 is freely available at
 - <http://ssi.is.s.u-tokyo.ac.jp/silc/>
 - Source (Unix/Linux, Windows, Mac OS X)
 - Precompiled binary package for Windows
 - Documentation, sample programs